

On the optimality of timer based caching policies

The role of hazard rates

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Problem formulation

System model

Optimal timer policy

Optimal non-anticipative policy

Asymptotic equivalence and optimality

Conclusions

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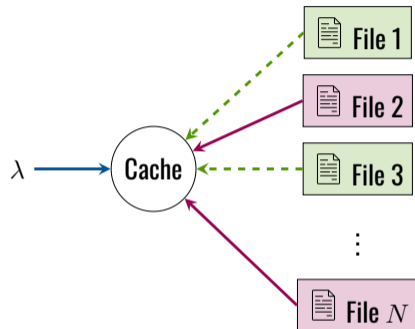
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The caching problem

- Consider a **cache system** with a catalog of N objects.
- Requests for objects arrive at random at rate λ .
- The cache can locally store $C < N$ of them.
- If item is in cache, we have a **hit**.



Objective: for a given arrival process, maximize the steady-state hit probability.

Populating a cache

Two main approaches

Eviction-based policies:

- Upon request arrival, check for presence, if new decide whether to store.
- If cache is full, **evict** a content based on some historical rule.

Example: Least-Recently-Used

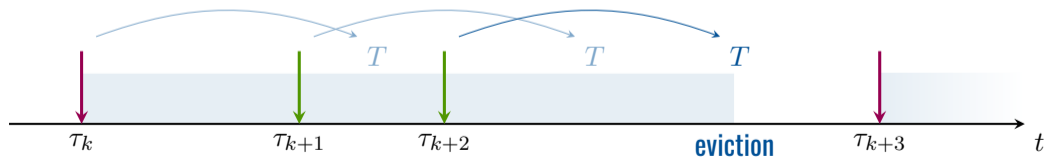
- Store the most recent C requests.
- If new request is present \rightarrow serve and move to the front of the queue.
- If not present \rightarrow retrieve, store at the front and drop the oldest one.

Populating a cache

Two main approaches

Timer based (TTL) policies:

- Upon request arrival for item i , check for presence.
- If new, store item and start a **timer** T_i to evict.
- If present, reset timer to T_i .
- Keep timers T_i such that **average** cache occupation is C .



- Eviction based policies work with a **fixed** cache size.
- Difficult to analyze: dynamics are coupled over requests.
- TTL policies have a **soft** cache constraint.
- But analysis **decouple** over requests, thus simpler to get results.

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What are the **optimal** policies in both families? Are they related?

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The classical arrival model is the **independent reference model**:

- Requests arrive as a Poisson process of intensity λ .
- Request is for item i with probability p_i (popularity).
- Poisson thinning: each request process is Poisson λp_i .
- Successive requests are **independent** with distribution $(p_i : i = 1, \dots, N)$.

Request arrival model

Beyond the IRM...

- **Problem:** caches work best when requests are **bursty**, i.e. successive requests are **correlated**.
- However, under the IRM we have purely random requests.

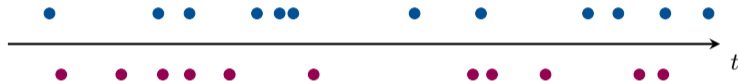
Point process approach [Fofack et al. 2014]:

- Assume requests for item i come from a **point process** of intensity $\lambda_i := \lambda p_i$.
- If inter-request times are **heavy tailed**, this can model burstiness.

Example: Pareto arrivals

Consider two items, with equal popularity...

■ Poisson arrivals:



Homogeneous

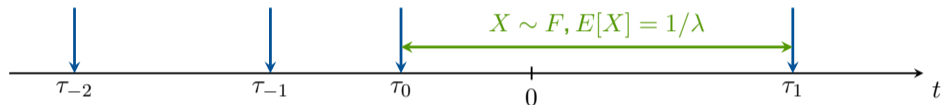
■ Heavy tailed arrivals (Pareto $\alpha = 2$):



Bursty!

A bit of point process theory...

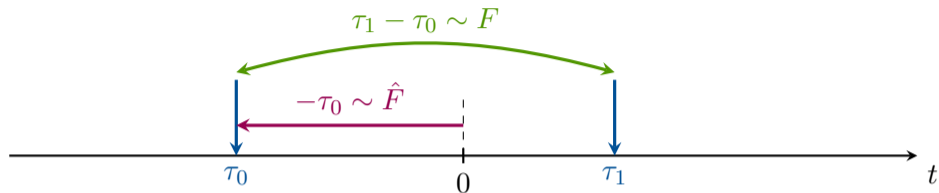
Let $N = \{\tau_k : k \in \mathbb{Z}\}$ be a **stationary point process** representing requests from an item:



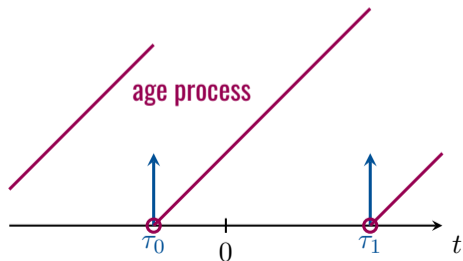
Two main probability measures:

- P : the steady-state probability, seen from an arbitrary point in time.
- P_N^0 : the **Palm** probability, measures things from the perspective of the **points**.

Age distribution at a random point in time



Age process:



Inter-arrival distribution:

$$F(t) := P_N^0(\tau_1 - \tau_0 \leq t), \quad E_N^0[\tau_1] = 1/\lambda.$$

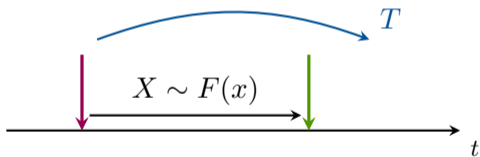
Age distribution:

$$\hat{F}(t) := P(-\tau_0 \leq t) = \lambda \int_0^t (1 - F(s)) ds,$$

Application: TTL policies

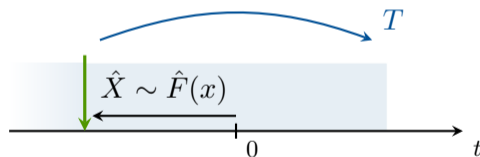
Consider a single item with a timer T and its request process:

Hit probability: next arrival occurs before timer expires.



$$\text{Hit probability} = F(T)$$

Occupation probability: probability that timer hasn't expired by 0 since last arrival.



$$\text{Avg. occupation} = \hat{F}(T)$$

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Choosing the optimal timers

Requests come from independent sources with intensities λ_i and inter-arrival distribution F_i :

Problem (Optimal TTL policy)

Choose timers $T_i \geq 0$ such that:

$$\max_{T_i \geq 0} \sum_i \lambda_i F_i(T_i)$$

subject to:

$$\sum_i \hat{F}_i(T_i) \leq C$$

Remark: non-convex non-linear program.

Choosing the optimal timers

Idea: Change of variables $u_i = \hat{F}_i(T_i)$ (occupation).

Problem (Optimal TTL policy)

Choose timers $T_i = \hat{F}_i^{-1}(u_i)$ such that:

$$\max_{u_i \in [0,1]} \sum_i \lambda_i F_i(\hat{F}_i^{-1}(u_i))$$

subject to:

$$\sum_i u_i \leq C$$

The hazard rate function

Define $G_i(u) := \lambda_i F_i(\hat{F}_i^{-1}(u))$, then:

$$\frac{\partial G_i}{\partial u} = \lambda_i f_i(\hat{F}_i^{-1}(u)) \frac{\partial \hat{F}_i^{-1}(u)}{\partial u} = \frac{\lambda_i f_i(\hat{F}_i^{-1}(u))}{\lambda_i (1 - F_i(\hat{F}_i^{-1}(u)))} = \eta_i(T_i)$$

where $\eta_i(t)$ is the **hazard rate function** of the inter-arrival distribution:

$$\eta_i(t) := \frac{f_i(t)}{1 - F_i(t)}$$

Idea: the hazard rate measures the probability that we have a request at time t , given that the current interval is larger than t .

Increasing hazard rates

Poisson arrivals: constant hazard rate (memoryless property), $\eta_i(t) \equiv \lambda_i \rightarrow$ objective is **linear**.

Increasing hazard rates: $\eta_i(t)$ increasing (more regular traffic) \rightarrow objective is **convex!**

Optimal TTL policy, constant or IHR, [F',Rodriguez, Paganini 18].

In both cases, the optimal TTL policy is **static**:

$$T_i^* = \infty, \quad (u_i^* = 1) \quad \text{for the } C \text{ contents with higher } \lambda_i$$

Decreasing hazard rates

- The **decreasing hazard rate** case corresponds to heavy tails and thus more bursty traffic \rightarrow where caching is more useful!
- If $\eta_i(t)$ is **decreasing**, objective is **concave**, we have a non-trivial optimum:

$$\mathcal{L}(u, \mu) = \sum_i \lambda_i F_i(\hat{F}^{-1}(u_i)) - \mu \left(\sum_i u_i - C \right)$$

- KKT conditions:

$$\eta_i(\hat{F}^{-1}(u_i^*)) = \eta_i(T_i^*) \geq \mu \quad \forall i, \quad \mu \left(\sum_i u_i^* - C \right) = 0$$

Optimal TTL policy, DHR, [F',Rodriguez, Paganini 18].

The optimal TTL caching policy for DHR is such that:

$$\eta_i(T_i^*) \geq \mu^*$$

for every stored content.

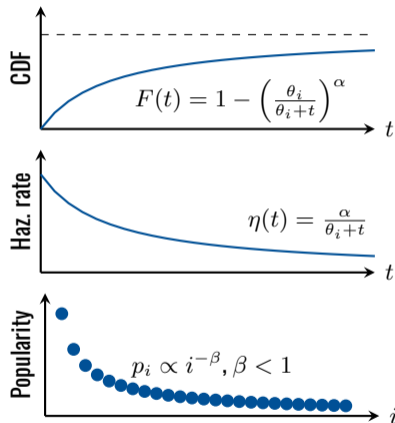
Idea: we have a fixed memory budget to allocate. $\eta_i(T_i)$ is the marginal increase in hit rate (utility) for enlarging the timer T_i .

Optimal allocation: equalize marginal utilities.

Parametric heavy tailed case

- For **Pareto** arrivals and **Zipf** popularities you can obtain a nice **fluid limit**.
- Let N go to ∞ and $C = cN$, then u_i^* has a **functional limit**.
- The hit probability is given by [FRP '18]:

$$H^* = (1 - \beta) \int_0^1 x^{-\beta} \left[1 - (1 - u^*(x))^{\frac{\alpha}{\alpha-1}} \right] dx,$$



Conclusions so far...

- The **hazard rate function** of F plays a crucial role in determining the optimal TTL policy!
- For IHR: just store the most popular content.
- For DHR: proper optimization problem, **equalize hazard rates**.
- Asymptotic analysis has **explicit expressions**.

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Back to replacement policies

- Assume now that you have a **fixed** capacity C . We have to decide which contents to store.
- Naïve idea: just keep the C most popular ones (higher λ_i). ¿Can we do better?

Problem

Given some independent stationary request processes with intensities λ_i , what is the **optimal non-anticipative** policy?

Idea: we should keep track of some **local notion** of intensity!

Consider a simple stationary point process N with intensity λ , defined in some probability space (Ω, \mathcal{F}, P) . Let some filtration $\{\mathcal{F}_t\}_{t \in \mathbb{R}}$ be a **history** of the process.

Define the **stochastic intensity** $\lambda(t)$ of N as:

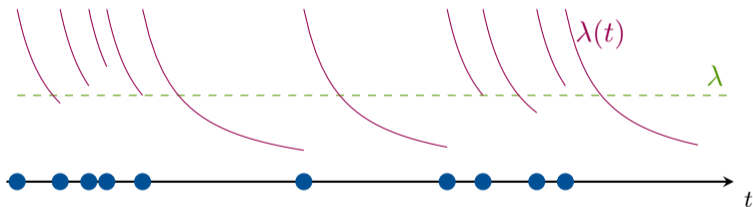
$$\lim_{h \rightarrow 0} \frac{1}{h} E[N((t, t + h]) \mid \mathcal{F}_t] = \lambda(t) \quad P - a.s.,$$

Idea: If the process is simple (isolated points), $E[N((t, t + h]) = \lambda h + o(h)$, so the **average** stochastic intensity is λ . But given the history, the value of $\lambda(t)$ may change.

Stochastic intensity

A local notion of intensity...

If traffic is **bursty**, the stochastic intensity rises near arrivals:



Stochastic intensity of a renewal process

- Let now N be a **renewal process** \rightarrow inter-request times are $iid \sim F$.
- Let \mathcal{F}_t be the **natural history** of the process (i.e. the information of points up to t).

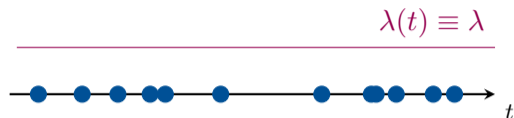
Theorem (cf. Brémaud 21)

Let $\eta(t) := f(t)/(1 - F(t))$ be the **hazard rate** function of F . Define:

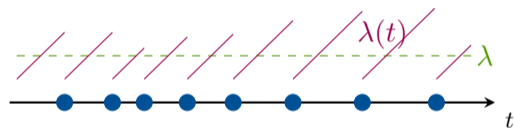
$$\lambda(t) = \eta(t - \tau_t^*),$$

where τ_t^* is the last point before t . Then $\lambda(t)$ is a stochastic intensity for (N, \mathcal{F}_t) .

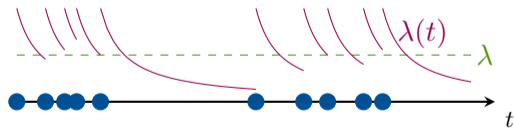
Some examples...



Constant hazard rate \rightarrow Poisson process.



Increasing hazard rate \rightarrow more periodic!



Decreasing hazard rate \rightarrow more bursty!

Non anticipative caching policies

- Consider a cache system fed by N independent renewal processes.
- Let $\mathcal{F}_T = \sigma(\{\mathcal{F}_t^i : i = 1, \dots, N\})$ their aggregate history.

Definition

A **non anticipative** caching policy is a \mathcal{F}_t **predictable** stochastic process

$$\mathcal{C} : \Omega \times \mathbb{R} \rightarrow 2^{\{1, \dots, N\}}$$

i.e. $\mathcal{C}(t) = \{i_1, \dots, i_C\}$ is the subset cached at time t , and only depends on the past history of item requests.

Focus now on a particular content i , its **hit process** is the point process given by:

$$H_i(B) = \sum_{n \in \mathbb{Z}} \mathbf{1}_{\{\tau_n^i \in B\}} \mathbf{1}_{\{i \in \mathcal{C}(\tau_n^i)\}}$$



Since $\mathbf{1}_{\{i \in \mathcal{C}(\tau_n^i)\}}$ is \mathcal{F}_t predictable, its stochastic intensity is:

$$h_i(t) = \lambda_i(t) \mathbf{1}_{\{i \in \mathcal{C}(t)\}}$$

i.e., $h_i = \lambda_i$ while $i \in \mathcal{C}$ and otherwise 0.

The hit process

The hit rate

If we now consider the aggregate of requests, the **total hit process** is given by:

$$H = \sum_{i=1}^N H_i$$

And its stochastic intensity is just:

$$h(t) = \sum_{i=1}^N h_i(t) = \sum_{i=1}^N \lambda_i(t) \mathbf{1}_{\{i \in \mathcal{C}(t)\}}$$

The hit rate and hit probabilities of the policies are given by:

$$\text{hit rate} = \lambda_H := E[h(t)], \quad \text{hit probability} := \frac{\lambda_H}{\lambda}.$$

Maximizing the hit rate

In order to maximize λ_H , consider the policy:

$$\mathcal{C}^*(t) = \{i_1, \dots, i_C\} \quad \text{such that} \quad \sum_{i \in \{i_1, \dots, i_C\}} \lambda_i(t) \text{ is maximized.}$$

Then, for any non-anticipative policy and for each realization:

$$h(t) = \sum_{i \in \mathcal{C}(t)} \lambda_i(t) \leq \sum_{i \in \mathcal{C}^*(t)} \lambda_i(t) = h^*(t).$$

Theorem (Towsley et al 22)

The **optimal non-anticipative policy** is to keep in the cache the C objects with the **highest stochastic intensity** at any time.

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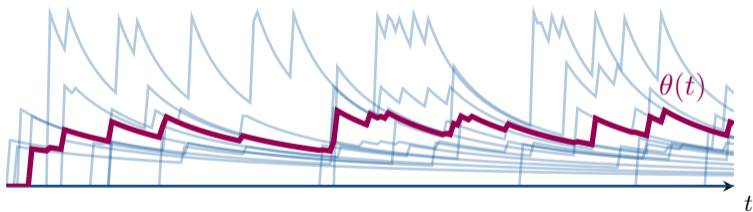
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The threshold process

We can rewrite this optimal policy as a **threshold** policy:

$$i \in C^*(t) \Leftrightarrow \lambda_i(t) \geq \theta(t) := \text{the } C \text{ largest stochastic intensity}$$

Example: Pareto requests, Zipf popularities, $N = 20, C = 4$.



We want to understand $\theta(t)$.

The threshold value in steady state

- Now we have N independent renewal processes with $\lambda_i(t)$.
- At time 0, we have a sample:

$$\{\lambda_1(0), \lambda_2(0), \dots, \lambda_N(0)\}$$

of independent, but **not identically distributed** random variables, with known distribution.

- The threshold $\theta(0)$ is the C -th **order statistic** (in decreasing order) of the sample.

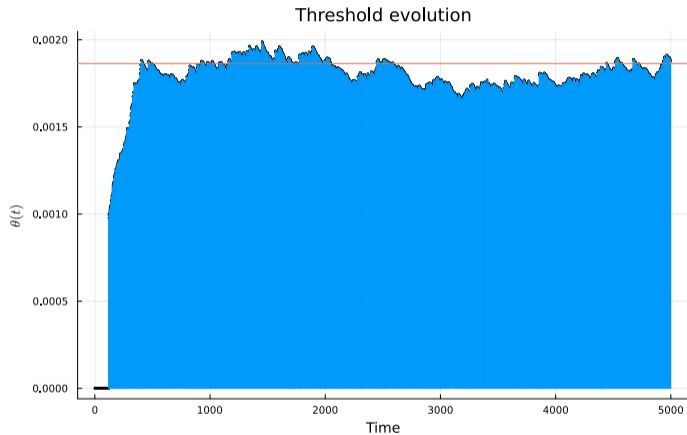
Problem: for non *iid* random variables, no closed form \rightarrow Can we say something about the large scale limit?

Theorem [F', Carrasco, Paganini, last week...]

Consider a cache system fed by N independent renewal processes with DHR inter-arrival times, and the optimal non-anticipative policy. Let $N \rightarrow \infty$ with $C = cN$. Then, in steady state:

- The (appropriately scaled) threshold $\theta_N(t)$ converges almost surely to a constant θ^* .
- θ^* is the dual value of the optimal TTL policy, i.e. the value that equalizes hazard rates.
- If popularities are slowly decaying (i.e. $\beta < 1$) then the hit probability of the optimal policy converges to H^* , the hit probability of the optimal TTL policy.

Simulation example

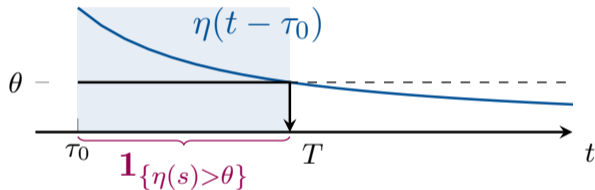


$N = 1000, C = 100$. Pareto $\alpha = 2$ requests, Zipf $\beta = 0.5$ popularities.

Why this happens?

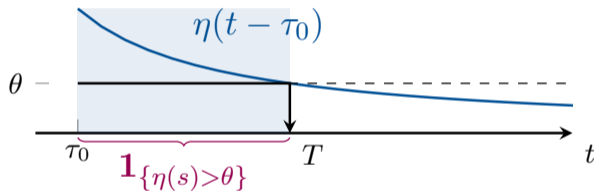
Why this happens?

Because, for decreasing hazard rates, the TTL policy is also a threshold policy!



Why this happens?

Because, for decreasing hazard rates, the TTL policy is also a threshold policy!



Key idea: replace the timer T_i by $\theta_i = \eta_i^{-1}(T_i)$, the corresponding hazard rate at the timer.

Some key steps in the proof

- Identify the distribution of $\lambda_i(t)$, the i -th stochastic intensity, with $\hat{F}_i(\eta_i^{-1}(\theta_i))$.
- Rewrite the optimal timer policy problem using the variables $\theta_i = \eta_i^{-1}(T_i)$.
- Use a statistics functional law of large numbers to prove that the sample empirical distribution of the sample $(\lambda_1(0), \dots, \lambda_N(0))$ converges to the average of the $\hat{F}_i \circ \eta_i^{-1}$.
- Identify the threshold in the average as the solution of the TTL optimization problem.

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Key takeaways...

- We analyzed two types of caching policies: replacement and TTL.
- We identified the **hazard rate** function as a crucial component of optimal policies.
- Using the point process framework, we can model burstiness and exactly compute asymptotics for TTL policies.
- We provide a large scale equivalence result for the optimal non-anticipative policy and the optimal TTL policy, enabling us to compute universal bounds on asymptotic performance!

- Analyze other distributions (not just Pareto), using the framework.
- Discuss the **increasing hazard rate** case:
 - Caching is a bad idea! If you receive a request, it's less likely to see it again!
 - The TTL policy is suboptimal
 - Key idea to explore: **pre-fetching!**
- Apply some **learning** techniques to estimate the hazard rates and the threshold in an online fashion.

Thank you!

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